

# Michael Y. Kersey

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## Objective Statement:

Computer science student looking for a software internship.

## EDUCATION

*B.S., Computer Science*

August 2023 - December 2026

San Jose State University, San Jose, CA, GPA: 3.94

## RELATED COURSEWORK

Data Structures and Algorithms, Linear Algebra, OOP, Info Security, Operating Systems (in progress), Computer Networks I (in progress), Computer Graphics (in progress)

## TECHNICAL SKILLS

*Computer Languages:* C++, Java, Python

## PROJECT EXPERIENCE

### SJSU Robotics (University Rover Challenge Team)

*Member of the Control Systems Subteam*

October 2023 - Present

- Develop device drivers in C++ for chips, such as the drv8825 (stepper motor driver) and tla2528 (GPIO expander).
- Experience reading chip datasheets and knowledge of communication protocols, such as i2c and UART.
- Open source contributor toward libhal (embedded framework the team uses for the rover) ([tla2528](#)) ([stm32 watchdog](#))

### Iron Claw Robotics 972 (First Robotics Competition Team)

*Team Mentor*

August 2023 - Present

- Advising on both technical and non-technical aspects of a 50-person robotics team.
- Providing guidance on task and code structuring and organization.
- Providing training on technical concepts such as Feed Forward and PID or basic programming.

*Programming Lead*

May 2022 - May 2023

- Coordinated with other programming leads to manage programming of a robot during the 3 month build and competition season.
- Led a team of 15 programmers and established code standards and architecture for the entire team.
- Reviewed and approved approximately [40 pull requests](#); ensuring quality of updates to the robot.
- Coordinated and developed a training curriculum for new programming team members during offseason
- Competed against 3,304 teams and finished as a final eight alliance, composed of 4 teams, in the global robotics championship competition ([link to record of season](#)).

*Member of Programming Subteam*

August 2020 - May 2022

- Utilized Java to develop code for the robot's climbing mechanism and other subsystems.
- Created the first wrapper library for controller inputs, for convenience and clarity, which is still used.

## Other Information

*Github Accounts:* <https://github.com/MichaelYKersey>, <https://github.com/PandaNinja10>

*Website Resume:* <https://michaelykersey.github.io/>

*Leetcode Profile:* <https://leetcode.com/u/MichaelYKersey/>

*Python*

- Used Python to script tasks such as generating templated text files from a json file and scraping data from a tab complete menu